

**IN THE CLAIMS:****Listing of Claims:**

1 **Claim 1.** (previously amended) An emitter locator system, comprising:

2 a mobile DF set, said set comprising a receiver for receiving incident signal  
3 transmissions;

4 a line of bearing (LOB) generating system in operative communication with said  
5 receiver and configured to generate lines of bearing responsive to said received signal  
6 transmissions;

7 an LOB error generating system in operative communication with said line of  
8 bearing generating system and configured to generate error bounds related to said lines of  
9 bearing, said line of bearing generating system and said LOB error generating system  
10 executed by a computing device, said computing device operatively generating a cross-  
11 over point, said cross-over point defined as the intersection of a pair of sequential real-  
12 time lines of bearing from said mobile DF set, each said line of bearing corresponding to  
13 a wireless transmission from said transmitter received by said mobile DF set and said  
14 computing device then estimates a future position of said transmitter in reference to said  
15 cross-over point;

16 a probability overlay generating system in operative communication with said  
17 LOB error generating system and configured to generate an overlay probability map  
18 responsive to said error bounds; and

19 display means for visually displaying said lines of bearing, said error bounds and  
20 said overlay map.

1 **Claim 2.** (previously amended) The system of Claim 1, wherein:

2 said incident signal transmissions are further defined by strength and clarity  
3 factors;

4        said line of bearing generating system further generates quality numbers for each  
5        said line of bearing responsive to said strength and clarity factors; and

6        said LOB error generating system generates said error bounds responsive to said  
7        quality numbers.

1        **Claim 3.** (previously amended) The system of Claim 2, further comprising a second  
2        DF set in communication with said mobile DF set, said second set comprising a receiver  
3        for receiving incidental signal transmissions, the system further comprising:

4        said line of bearing generating system;

5        said LOB error generating system;

6        said probability overlay generating system; and

7        said display means for further visually displaying said lines of bearing, said error  
8        bounds and said overlay map, said lines of bearing generated by said mobile DF set and  
9        said second DF set.

1        **Claim 4.** (original) The system of Claim 3, wherein said display means of said mobile  
2        DF set further displays said lines of bearing generated by said second DF set.

1        **Claim 5.** (original) The system of Claim 2, wherein said mobile DF set further  
2        comprises a position estimating system for determining the spacial location of said  
3        transmitter responsive to said lines of bearing and said LOB errors.

1        **Claim 6.** (original) The system of Claim 5, wherein said display means further displays  
2        said spacial location of said transmitter.

1        **Claim 7.** (original) The system of Claim 6, wherein said probability overlay generating  
2        system is further responsive to said spacial location of said transmitter.

1        **Claim 8.** (original) The system of Claim 7, wherein said probability overlays comprise  
2        a two-dimensional composite of concentric shapes.

1 **Claim 9.** (previously amended) The system of Claim 8, wherein said concentric shapes  
2 comprise an inner shape concentric to an outer shape, said inner shape configuration  
3 representative of said error bounds having relatively small values and said outer shape  
4 configuration representative of said error bounds having relatively large values.

1 **Claim 10.** (previously amended) A direction-finding method comprising the steps of:  
2 establishing a cross-over position point;  
3 relocating a receiver to a new receiver spacial location;  
4 said receiver at said new receiver position receiving a transmission from a  
5 transmitter at a transmitter position;  
6 determining a real-time line of bearing from said receiver to said transmitter;  
7 generating a connecting vector from said real-time line of bearing to said cross-  
8 over position point; and  
9 identifying a real-time position of said transmitter along said connecting vector;-  
10 displaying said real-time position on a user display panel; and  
11 generating and displaying an probability overlay map responsive to said real-time  
12 position and a quality factor on said user display panel.

1 **Claim 11.** (original) The method of Claim 10, wherein said identifying step further  
2 comprises assigning a probability factor to said real-time position of said transmitter  
3 responsive to said quality factor and said probability overlay map generating and  
4 displaying is responsive to said probability factor.

1 **Claim 12.** (original) The method of Claim 11, further comprising a repeating step to  
2 repeat said relocating, receiving, determining, generating, identifying, displaying and  
3 generating steps until said probability factor exceeds a predetermined threshold value.

1 **Claim 13.** (original) The method of Claim 11, further comprising a repeating step to  
2 repeat said relocating, receiving, determining, generating, identifying, displaying and  
3 generating steps until said probability factor meets a user-defined threshold value.

1 **Claim 14.** (original) The method of Claim 11, further comprising a repeating step to  
2 repeat said relocating, receiving, determining, generating, identifying, displaying and  
3 generating steps until a user terminates said direction finding method.